

LINEARNI OPERATORI

$$f: V_1 \rightarrow V_2$$

$$(\forall \alpha, \beta \in F) (\forall x, y \in V_1) \quad f(\alpha x + \beta y) = \alpha f(x) + \beta f(y)$$

50 Neka je M_2 vekt. p. kvadratnih matrica nad F ,
i $f: M_2 \rightarrow M_2$ definisano sa: $(\forall x \in M_2) \quad f(x) = x \cdot M$
pri čemu je $M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ fiksirana matrica iz M_2

a) Dokazati da je f linearni operator.

b) Odrediti matricu operatora F u odnosu na bazu:

$$\left\{ \overset{E_1}{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}, \overset{E_2}{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}, \overset{E_3}{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}, \overset{E_4}{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}} \right\}$$

a) $X, Y \in M_2, \alpha, \beta \in F$

$$\begin{aligned} f(\alpha X + \beta Y) &= (\alpha X + \beta Y) \cdot M = (\alpha X)M + (\beta Y)M \\ &= \alpha(XM) + \beta(YM) = \alpha f(X) + \beta f(Y) \end{aligned}$$

$$\begin{array}{l} V_1; B_1 = \{e_1, \dots, e_m\}; \quad \dim V_1 = m \\ V_2; B_2 = \{f_1, \dots, f_m\}; \quad \dim V_2 = m \\ (\forall x \in V_1) \quad f(x) = Ax \end{array}$$

$$f(e_1) = a_{11}f_1 + a_{12}f_2 + \dots + a_{1n}f_n$$

$$f(e_2) = a_{21}f_1 + a_{22}f_2 + \dots + a_{2n}f_n$$

\vdots

$$f(e_m) = a_{m1}f_1 + a_{m2}f_2 + \dots + a_{mn}f_n$$

$$\Rightarrow A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

$$f(e_1) = A \cdot e_1 = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} = a_{11}f_1 + \dots + a_{m1}f_m$$

$$f(E_1) = E_1 \cdot M = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = (a, b, 0, 0)$$

$$f(E_2) = E_2 \cdot M = \begin{bmatrix} c & d \\ 0 & 0 \end{bmatrix} = (c, d, 0, 0)$$

$$f(E_3) = E_3 \cdot M = \begin{bmatrix} 0 & 0 \\ a & b \end{bmatrix} = (0, 0, a, b)$$

$$f(E_4) = E_4 \cdot M = \begin{bmatrix} 0 & 0 \\ c & d \end{bmatrix} = (0, 0, c, d)$$

$$\Rightarrow A = \begin{bmatrix} a & c & 0 & 0 \\ b & d & 0 & 0 \\ 0 & 0 & a & c \\ 0 & 0 & b & d \end{bmatrix}$$

51. - 11 - $f(x) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot X$

Rz. a) ✓

b) $A = \begin{bmatrix} a & 0 & b & 0 \\ 0 & a & 0 & b \\ c & c & d & d \\ 0 & c & 0 & d \end{bmatrix}$

52. $f: M_2 \rightarrow M_2$ nad polnem R

$$f(X) = A \cdot X \cdot B, \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}$$

a) lin. op. b) Naci matricu operatora...

R_f

$$A_f = \begin{bmatrix} ae & ag & be & bg \\ af & ah & bf & bh \\ ce & cg & de & dg \\ cf & ch & df & dh \end{bmatrix}$$

53. $f: M_2 \rightarrow M_2$

$$f(x) = AX + XB$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}, \quad A, B \in M_2$$

a) Da li je lin. op.

b) Naći matricu operatora f u odnosu na bazu:

$$B = \left\{ \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right\} \rightarrow \text{nije stand. baza jer elementi nisu isti}$$

$$f(E_1) = AE_1 + E_1B = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} 0 & b \\ g & d+h \end{bmatrix}$$

$$= 0 \cdot E_1 + b \cdot E_2 + g \cdot E_2 + (d+h) \cdot E_1$$

$$= (d+h, g, b, 0)$$

$$A_f = \begin{pmatrix} d+h & f & c & 0 \\ g & d+e & 0 & c \\ b & 0 & a+h & f \\ 0 & b & g & a+e \end{pmatrix}$$

Standardna baza: $B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$

$$A_f = \left(\begin{array}{cc|cc} ae & g & b & 0 \\ f & a+h & 0 & b \\ c & 0 & d+e & g \\ 0 & c & f & d+h \end{array} \right)$$

centralna sim.

54. Dokažati da postoji jedinstven lin. operator 3D vektorskog prostora koji prevodi vektore a_1, a_2, a_3 u b_1, b_2, b_3 , redom. Imaći matricu tog operatora u istoj bazi u kojoj su date i koordinate tih vektora.

a) $a_1 = (2, 3, 5), a_2 = (0, 1, 2), a_3 = (1, 0, 0)$

$b_1 = (1, 1, 1), b_2 = (1, 1, -1), b_3 = (2, 1, 2)$

(b) $a_1 = (2, 0, 3), a_2 = (4, 1, 5), a_3 = (3, 1, 2)$

$b_1 = (1, 2, -1), b_2 = (4, 5, -2), b_3 = (1, -1, 1)$

$$A = \frac{1}{3} \begin{pmatrix} -6 & 11 & 5 \\ -12 & 13 & 10 \\ 6 & -5 & -5 \end{pmatrix}$$

Tr. lin. operator prostora U u prostor V je potpuno određen, ako su poznate slike elemenata baze prostora U.

a_1, a_2, a_3 lin. nez.?

$$\lambda_1 a_1 + \lambda_2 a_2 + \lambda_3 a_3 = 0$$

$$\lambda_1 = \lambda_2 = \lambda_3 = 0 \Rightarrow a_1, a_2, a_3 \text{ su lin. nezavisni}$$

Pošto je prostor trodim. i a_1, a_2, a_3 su lin. nez. \Rightarrow čine bazu prostora. $B = (a_1, a_2, a_3)$

$\Rightarrow \exists!$ linearni operator $f: V \rightarrow V$

$$\begin{aligned} f(a_1) &= f(2, 3, 5) = f(2 \cdot e_1 + 3e_2 + 5e_3) \\ &\stackrel{f \text{ lin. op.}}{=} 2f(e_1) + 3f(e_2) + 5f(e_3) = (1, 1, 1) \text{ baza} \\ &= e_1 + e_2 + e_3 \end{aligned} \quad \{e_1, e_2, e_3\} \quad (1)$$

$$f(a_2) = f(0, 1, 2) = f(e_2) + 2f(e_3) = e_1 + e_2 - e_3 \quad (2)$$

$$f(a_3) = f(1, 0, 0) = f(e_1) = 2e_1 + e_2 + 2e_3 \quad (3)$$

Rješavamo sis. po $f(e_i)$:

$$2f(e_1) + 3f(e_2) + 5f(e_3) = e_1 + e_2 + e_3$$

$$f(e_2) + 2f(e_3) = e_1 + e_2 - e_3$$

$$f(e_1) = 2e_1 + e_2 + 2e_3$$

$$f(e_1) = 2e_1 + e_2 + 2e_3 = (2, 1, 2)$$

$$2 \cdot (2e_1 + e_2 + 2e_3) + 3f(e_2) + 5f(e_3) = e_1 + e_2 + e_3$$

$$f(e_2) + 2f(e_3) = e_1 + e_2 - e_3$$

$$3f(e_2) + 5f(e_3) = -3e_1 - e_2 - 3e_3 \quad \leftarrow$$

$$f(e_2) + 2f(e_3) = e_1 + e_2 - e_3 \quad (/3)$$

$$-f(e_3) = -6e_1 - 4e_2 \Rightarrow f(e_3) = (6, 4, 0)$$

$$f(e_2) = -11e_1 - 7e_2 - e_3 \Rightarrow f(e_2) = (-11, -7, -1)$$

$$\Rightarrow A_f = \begin{pmatrix} 2 & -11 & 6 \\ 1 & -7 & 4 \\ 2 & -1 & 0 \end{pmatrix}$$

55. Neka je V trodim. v. p. Ispitati kojim od sledećih preslikavanja $f: V \rightarrow V$ lin. operatori. U slučaju da su lin. operatori, naći njihove matrice u istoj bazi u kojoj su zadane koordinate vektora x i $f(x)$.

a) $f(x) = f(x_1, x_2, x_3) = (x_2 + x_3, 2x_1 + x_3, 3x_1 - x_2 + x_3)$

b) $f(x) = (x_1, x_2 + 1, x_3 + 2)$

c) $f(x) = (2x_1 + x_2, x_1 + x_3, x_3^2)$ nije

d) $f(x) = (x_1 - x_2 + x_3, x_3, x_2)$ jest. $A_f = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$

a) $\forall \alpha, \beta \in F, \forall x, y \in V$

$$\begin{aligned} f(\alpha x + \beta y) &= f(\alpha x_1 + \beta y_1, \alpha x_2 + \beta y_2, \alpha x_3 + \beta y_3) \\ &= ((\alpha x_2 + \beta y_2) + (\alpha x_3 + \beta y_3), 2(\alpha x_1 + \beta y_1) + \alpha x_3 + \beta y_3, 3(\alpha x_1 + \beta y_1) - (\alpha x_2 + \beta y_2) + (\alpha x_3 + \beta y_3)) \end{aligned}$$

$$= \dots = (\alpha(x_2 + x_3) + \beta(y_2 + y_3), \alpha(2x_1 + x_3) + \beta(2y_1 + y_3), \alpha(3x_1 + x_2 + x_3) + \beta(3y_1 - y_2 + y_3)) =$$

$$= \alpha(x_2 + x_3, 2x_1 + x_3, 3x_1 - x_2 + x_3) + \beta(y_2 + y_3, 2y_1 + y_3, 3y_1 - y_2 + y_3) = \alpha f(x) + \beta f(y)$$

1. naćim:

$$B = \{e_1, e_2, e_3\}$$

$$f(e_1) = f(1, 0, 0) = (0, 2, 3)$$

$$f(e_2) = f(0, 1, 0) = (1, 0, -1)$$

$$f(e_3) = f(0, 0, 1) = (1, 1, 1)$$

$$\Rightarrow A_f = \begin{pmatrix} 0 & 1 & 1 \\ 2 & 0 & 1 \\ 3 & -1 & 1 \end{pmatrix}$$

2. naćim (u ovom slučaju možemo direktno odrediti mat. operatora)

$$A_f; f(x) = A_f \cdot x$$

$$\begin{pmatrix} x_2 + x_3 \\ 2x_1 + x_3 \\ 3x_1 - x_2 + x_3 \end{pmatrix} = A_f \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \Rightarrow A_f = \begin{pmatrix} 0 & 1 & 1 \\ 2 & 0 & 1 \\ 3 & -1 & 1 \end{pmatrix}$$

da bi bilo $f(x)$ treba:

b) $f(\alpha x + \beta y) \stackrel{?}{=} \alpha f(x) + \beta f(y)$

$$(\alpha x_1 + \beta y_1, \alpha x_2 + \beta y_2 + 1, \alpha x_3 + \beta y_3 + 2) = (\alpha x_1, \alpha x_2 + \alpha, \alpha x_3 + 2\alpha) + (\beta y_1, \beta y_2 + \beta, \beta y_3 + 2\beta)$$

$$\neq (\alpha x_1 + \beta y_1, \alpha x_2 + \beta y_2 + \alpha + \beta, \alpha x_3 + \beta y_3 + 2(\alpha + \beta))$$

nije lin. operator!

5.6. Neka je P_3 v.p. polinoma stepena ≤ 3 nad poljem \mathbb{R} , i $f: P_3 \rightarrow P_3$ definisano sa:

$$f(P(t)) = \int_0^1 P(t+\tau) d\tau \quad \forall P \in P_3$$

a) Dokazati da je f lin. operator.

b) Naći matricu operatora f u odnosu na bazu $\{1, t, t^2, t^3\}$

a) $(\forall \alpha, \beta \in \mathbb{R}) (\forall P, Q \in P_3)$

$$\begin{aligned} f(\alpha P + \beta Q) &= \int_0^1 (\alpha P + \beta Q)(t+\tau) d\tau = \int_0^1 (\alpha P(t+\tau) + \beta Q(t+\tau)) d\tau = \\ &= \int_0^1 (\alpha P(t+\tau) + \beta Q(t+\tau)) d\tau \\ &= \alpha \int_0^1 P(t+\tau) d\tau + \beta \int_0^1 Q(t+\tau) d\tau = \alpha f(P) + \beta f(Q) \end{aligned}$$

b) $f(1) = \int_0^1 1 d\tau = 1 = (1, 0, 0, 0) = (1 \cdot 1, 0 \cdot t, 0 \cdot t^2, 0 \cdot t^3)$

$f(t) = \int_0^1 (t+\tau) d\tau = \left(t\tau + \frac{\tau^2}{2} \right) \Big|_0^1 = t + \frac{1}{2} = \left(\frac{1}{2}, 1, 0, 0 \right)$ $P(t) = t$

$f(t^2) = \int_0^1 (t+\tau)^2 d\tau = \int_0^1 (t^2 + 2t\tau + \tau^2) d\tau = \left(t^2\tau + 2t \frac{\tau^2}{2} + \frac{\tau^3}{3} \right) \Big|_0^1 = t^2 + t + \frac{1}{3} = \left(\frac{1}{3}, 1, 1, 0 \right)$

$$f(t^3) = \int_0^1 (t+r)^3 dr = \int_0^1 (t^3 + 3t^2r + 3tr^2 + r^3) dr = \left(t^3r + 3t^2 \frac{r^2}{2} + 3t \frac{r^3}{3} + \frac{r^4}{4} \right) \Big|_0^1$$

$$= t^3 + 3t^2 \frac{1}{2} + t + \frac{1}{4} = \left(\frac{1}{4}, \frac{3}{2}, 1, t \right)$$

$$\Rightarrow A_f = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ 0 & 1 & 1 & \frac{1}{2} \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

57. Neka je V skup svih realnih fja oblika $f(x) = e^{ax} \cdot P(x)$, gdje je $a \in \mathbb{R}$, $a \neq 0$, a $P(x)$ je realan polinom stepena ≤ 3 . Dokazati da je operator definisan sa $D(f) = f'$ linearan u prostora V i naći matricu tog operatora u odnosu na bazu $B = \{e^{ax}, x e^{ax}, x^2 e^{ax}, x^3 e^{ax}\}$

a) $D(\alpha f + \beta g) = \dots = \alpha D(f) + \beta D(g)$

b) $\text{mat}_B D = \begin{pmatrix} a & 1 & 0 & 0 \\ 0 & a & 2 & 0 \\ 0 & 0 & a & 3 \\ 0 & 0 & 0 & a \end{pmatrix}$

58. Neka je $P_m[x]$ v.p. pol. stepena $\leq m$ nad \mathbb{R} i A preslikavanje definisano sa:
 $A(p(x)) = (cx+d)^m \cdot P\left(\frac{ax+b}{cx+d}\right)$, $a, b, c, d \in \mathbb{R}$, $ad-bc \neq 0$

a) Dokazati da je A lin. op. prostora $P_m[x]$

b) Naći mat. operatora u odnosu na bazu $\{1, x, x^2, \dots, x^m\}$ za $a=d=0$, $b=c=1$

$$\begin{aligned} A(\alpha P + \beta Q) &= (cx+d)^m (\alpha P + \beta Q) \left(\frac{ax+b}{cx+d} \right) \\ &= \dots = (cx+d)^m \left(\alpha P \left(\frac{ax+b}{cx+d} \right) + \beta Q \left(\frac{ax+b}{cx+d} \right) \right) \\ &= \alpha (cx+d)^m P \left(\frac{ax+b}{cx+d} \right) + \beta (cx+d)^m Q \left(\frac{ax+b}{cx+d} \right) = \alpha A(P) + \beta A(Q) \end{aligned}$$

b) $a=d=0, b=c=1$

$$A(P) = x^m \cdot P\left(\frac{1}{x}\right)$$

$$A(1) = x^m \cdot 1 = x^m = (0, 0, \dots, 0, 1)$$

$$A(x) = x^m \cdot \frac{1}{x} = x^{m-1} = (0, \dots, 0, 1, 0)$$

\vdots

$$A(x^m) = x^m \cdot \frac{1}{x^m} = 1 = (1, 0, \dots, 0)$$

$$P_1 = \frac{1}{x}$$

$$P(x^m) = \frac{1}{x^m}$$

$$\text{mat}_B A = \begin{pmatrix} 0 & 0 & \dots & 1 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 1 & \dots & 0 \\ 1 & 0 & \dots & 0 \end{pmatrix}$$

39 Linearan operator u prostoru $P_2[x]$ realnih pol. stepena ≤ 2 , ima matricu u odnosu na bazu $\{1, x, x^2\}$; ovakvu: $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$

Naći matricu tog operatora u odnosu na bazu: $\{3x^2+x+1, x^2+3x+2, 2x^2+x+3\}$

treba naći sliku operatora i izraziti preko vekt.

Uputa: Naći sliku: $f(3x^2+x+1) = \dots = d_1(3x^2+x+1) + d_2(x^2+3x+2) + d_3(2x^2+x+3)$ i ostale ... , a gđe za sveku kol.

$$\Rightarrow \text{mat}_B f = \begin{pmatrix} d_1 & & \\ d_2 & & \\ d_3 & & \end{pmatrix}$$

$$R_j: \frac{1}{17} \begin{pmatrix} -7 & 12 & 12 \\ 2 & 16 & -1 \\ 18 & -9 & 8 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$f(3x^2+x+1) = d_1(3x^2+x+1) + d_2(x^2+3x+2) + d_3(2x^2+x+3)$$

$$(3d_1 + d_2 + 2d_3)x^2 + (d_1 + 3d_2 + d_3)x + (d_1 + 2d_2 + 3d_3) = 3 \cdot 1 + x + x^2$$

$$3d_1 + d_2 + 2d_3 = 1$$

$$d_1 + 3d_2 + d_3 = 1$$

$$d_1 + 2d_2 + 3d_3 = 3$$

$$D = \begin{vmatrix} 3 & 1 & 2 \\ 1 & 3 & 1 \\ 1 & 2 & 3 \end{vmatrix} \begin{vmatrix} 0 & -8 & -1 \\ 1 & 3 & 1 \\ 0 & -1 & 2 \end{vmatrix} = -1 \cdot (-16 - 1) = 17$$

$$D_1 = \begin{vmatrix} 1 & 1 & 2 \\ 1 & 3 & 1 \\ 3 & 2 & 3 \end{vmatrix} \begin{vmatrix} 1 & 2 \\ 0 & -1 \end{vmatrix} = -6 + 1 = -7$$

$$L_1 = \frac{D_1}{D} = \frac{-7}{17}$$

$$D_2 = \begin{vmatrix} 3 & 1 & 2 \\ 1 & 1 & 1 \\ 1 & 3 & 3 \end{vmatrix} \begin{vmatrix} 3 & 1 & 2 \\ 0 & -1 \\ -8 & 0 & -3 \end{vmatrix} = -1 \cdot (6 - 8) = 2$$

$$L_2 = \frac{D_2}{D} = \frac{2}{17}$$

$$D_3 = \begin{vmatrix} 3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 2 & 3 \end{vmatrix} \begin{vmatrix} 3 & 1 & 1 \\ 2 & 2 & 0 \\ -8 & -1 & 0 \end{vmatrix} = 1 \cdot (2 + 16) = 18$$

$$L_3 = \frac{D_3}{D} = \frac{18}{17}$$

$$f(3x^2+x+1) = 3 \cdot f(x^2) + f(x) + f(1) \quad \text{zato što je lin. operator}$$

$$= 3 \cdot 1 + x + x^2 = d_1(3x^2+x+1) + d_2(x^2+3x+2) + d_3(2x^2+x+3)$$

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

mat. u odnosu na $\{1, x, x^2\}$

$$\Rightarrow f(1) = 0 \cdot 1 + 0 \cdot x + 1 \cdot x^2$$

$$f(x) = 0 \cdot 1 + 1 \cdot x + 0 \cdot x^2$$

$$f(x^2) = 1 \cdot 1 + 0 \cdot x + 0 \cdot x^2$$

$$1(x^2+3x+2) = 1(x^2) + 3(1x) + 2(1) = 1 + 3x + 2x^2$$

$$= 1 + 3x + 2x^2 = d_1(3x^2+x+1) + d_2(x^2+3x+2) + d_3(2x^2+x+3)$$

$$3d_1 + d_2 + 2d_3 = 2 \quad | \cdot (-2)$$

$$d_1 + 3d_2 + d_3 = 3 \quad \leftarrow$$

$$d_1 + 2d_2 + 3d_3 = 1 \quad | \cdot (-1) \leftarrow$$

$$3d_1 + d_2 + 2d_3 = 2 \quad \leftarrow$$

$$d_2 - 2d_3 = 2 \quad | \cdot (-1)$$

$$\begin{array}{r} -5d_1 \quad -d_3 = -3 \end{array}$$

$$5d_1 + d_3 = 0 \quad \leftarrow$$

$$\begin{array}{r} -5d_1 \quad -d_3 = -3 \quad | \cdot 4 \end{array}$$

$$\begin{array}{r} -17d_1 = -12 \quad \left| d_1 = \frac{12}{17} \right| \end{array}$$

$$d_2 = 2 + 2d_3 = 2 + \frac{18}{17} = \frac{26}{17}$$

$$d_2 = 2 + 2d_3 = 2 + \frac{18}{17} = \frac{26}{17}$$

$$1(2x^2+x+3) = 2(1x^2) + 1(1x) + 3(1)$$

$$2 + x + 3x^2 = d_1(3x^2+x+1) + d_2(x^2+3x+2) + d_3(2x^2+x+3)$$

$$3d_1 + d_2 + 2d_3 = 3$$

$$d_1 + 3d_2 + d_3 = 1$$

$$d_1 + 2d_2 + 3d_3 = 2$$

$$D = \begin{vmatrix} 3 & 1 & 2 \\ 1 & 3 & 1 \\ 1 & 2 & 3 \end{vmatrix} = \begin{vmatrix} 0 & -8 & -1 \\ 1 & 3 & 1 \\ 0 & -1 & 2 \end{vmatrix} = -(-16 - 1) = 17$$

$$d_1 = \frac{12}{17}$$

$$D_1 = \begin{vmatrix} 3 & 1 & 2 \\ 1 & 3 & 1 \\ 2 & 2 & 3 \end{vmatrix} = \begin{vmatrix} 3 & -2 & -1 \\ 1 & 2 & 0 \\ 2 & 0 & 1 \end{vmatrix} = \begin{vmatrix} 5 & -2 & -1 \\ 1 & 2 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 10 + 2 = 12$$

$$D_2 = \begin{vmatrix} 3 & 1 & 2 \\ 1 & 3 & 1 \\ 1 & 2 & 3 \end{vmatrix} = \begin{vmatrix} 3 & 0 & -1 \\ 1 & 0 & 0 \\ 1 & -1 & 2 \end{vmatrix} = -1 \cdot (3 \cdot 0 + 1 \cdot 1) = -1$$

$$d_2 = \frac{1}{17}$$

$$D_3 = \begin{vmatrix} 3 & 1 & 2 \\ 1 & 3 & 1 \\ 1 & 2 & 2 \end{vmatrix} = \begin{vmatrix} 3 & 1 & 0 \\ 1 & 3 & 0 \\ 1 & 2 & 1 \end{vmatrix} = 1 \cdot (9 - 1) = 8$$

$$d_3 = \frac{8}{17}$$

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 Preslikavanje $\mathcal{A}: V \rightarrow W$ u odnosu na baze $\{e_1, e_2, e_3\}$ prostora V i $\{f_1, f_2\}$ prostora W ima matricu $\begin{pmatrix} 0 & 1 & 2 \\ 3 & 4 & 5 \end{pmatrix}$. Naći matricu preslikavanja \mathcal{A} , u odnosu na baze $\{e_1, e_1+e_2, e_1+e_2+e_3\}$ prostora V i $\{f_1, f_1+f_2\}$ prostora W .

$$\left. \begin{aligned} \mathcal{A}(e_1) &= \alpha_1 \cdot f_1 + \alpha_2 (f_1 + f_2) \\ \mathcal{A}(e_1) &= 0 \cdot f_1 + 3 \cdot f_2 \end{aligned} \right\} \Rightarrow \alpha_1 + \alpha_2 = 0$$

$$\alpha_2 = 3 \Rightarrow \alpha_1 = -3$$

$$\left. \begin{aligned} \mathcal{A}(e_1+e_2) &= \alpha_1 \cdot f_1 + \alpha_2 (f_1 + f_2) \\ \mathcal{A}(e_1+e_2) &= \mathcal{A}(e_1) + \mathcal{A}(e_2) \\ &= 0 \cdot f_1 + 3 \cdot f_2 + \alpha_1 \cdot f_1 + \alpha_2 \cdot f_2 \end{aligned} \right\} \Rightarrow \alpha_1 + \alpha_2 = 1$$

$$\alpha_2 = 7 \Rightarrow \alpha_1 = -6$$

$$\left. \begin{aligned} \mathcal{A}(e_1+e_2+e_3) &= \alpha_1 \cdot f_1 + \alpha_2 (f_1 + f_2) \\ \mathcal{A}(e_1+e_2+e_3) &= \mathcal{A}(e_1) + \mathcal{A}(e_2) + \mathcal{A}(e_3) \\ &= 0 \cdot f_1 + \alpha_1 \cdot f_1 + 3 \cdot f_2 + \alpha_2 \cdot f_2 \end{aligned} \right\} \Rightarrow \alpha_1 + \alpha_2 = 3$$

$$\alpha_2 = 12 \Rightarrow \alpha_1 = -9$$

$$\begin{pmatrix} -3 & -6 & -9 \\ 3 & 7 & 12 \end{pmatrix}$$

Matrica linearnog prostora \mathbb{R}^3 u bazi $\{\overset{e_1}{(2, -6, 7)}, \overset{e_2}{(-16, 7, -13)}, \overset{e_3}{(9, -3, 7)}\}$ je $\begin{pmatrix} 1 & -18 & 15 \\ -1 & -22 & 20 \\ 1 & -25 & 22 \end{pmatrix}$. Naći matricu istog operatora, ali u bazi $\{\overset{x_1}{(1, -2, 1)}, \overset{x_2}{(3, -1, 2)}, \overset{x_3}{(2, 1, 2)}\}$.

$$\mathcal{A}(e_1) = 1 \cdot e_1 - 1 \cdot e_2 + 1 \cdot e_3$$

1. izraziti preob e_1, e_2, e_3
 $\alpha_1 e_1 + \alpha_2 e_2 + \alpha_3 e_3$

$$\mathcal{A}(1, -2, 1) = \alpha_1 \cdot (1, -2, 1) + \alpha_2 \cdot (3, -1, 2) + \alpha_3 \cdot (2, 1, 2) \quad 3 \text{ sistema}$$

$$\begin{aligned} \alpha_1 + 3\alpha_2 + 2\alpha_3 &= 1 \\ -2\alpha_1 - \alpha_2 + \alpha_3 &= -2 \\ \alpha_1 + 2\alpha_2 + 2\alpha_3 &= 1 \end{aligned}$$

$$\alpha_1 = 1 - 3\alpha_2 - 2\alpha_3$$

i matrica kad se bude radila još 3 sys

$$\mathcal{A} = \begin{bmatrix} 1 & 2 & 2 \\ 3 & -1 & -2 \\ 2 & -3 & 1 \end{bmatrix}$$

2. Neka je $T: V \rightarrow W$, linearni operator.

$$\text{Ker } T = \{x \in V \mid Tx = 0\}, \quad 0 \in W - \text{jezero operatora}$$

0_W ; $\text{Ker } T \subseteq V$

$$\text{Im } T = \{Tx \mid x \in V\}, \quad \text{slika operatora}$$

$$\text{def } T = \dim(\text{Ker } T) \quad \text{defekt operatora}$$

$$\text{rang } T = \dim(\text{Im } T) \quad \text{rang operatora}$$

T: $T: V \rightarrow V$ onda važi; sledede:

$$\dim V = \text{rang } T + \text{def } T$$

62. Neka je lin. operator $T: \mathbb{R}^3 \rightarrow \mathbb{R}^4$ definisan sa

$$T(1, 0, 0) = (0, 1, 0, 2)$$

$$T(0, 1, 0) = (0, 1, 1, 0)$$

$$T(0, 0, 1) = (0, 1, -1, 4)$$

Naći $\text{Ker } T$, $\text{def } T$, $\text{Im } T$ i $\text{rang } T$.

$$\text{Ker } T = \{x \in \mathbb{R}^3 \mid Tx = 0\}$$

$$(0, 0, 0, 0)$$

$$Tx = T(x_1, x_2, x_3) = T(x_1(1, 0, 0) + x_2(0, 1, 0) + x_3(0, 0, 1))$$

pošto je linearan:

$$= x_1 T(1, 0, 0) + x_2 T(0, 1, 0) + x_3 T(0, 0, 1)$$

$$= x_1(0, 1, 0, 2) + x_2(0, 1, 1, 0) + x_3(0, 1, -1, 4)$$

$$= \dots = (0, x_1 + x_2 + x_3, x_2 - x_3, 2x_1 + 4x_3) = (0, 0, 0, 0)$$

$$x_1 + x_2 + x_3 = 0 \quad x_1 = -2x_3$$

$$x_2 - x_3 = 0 \Rightarrow x_2 = x_3$$

$$2x_1 + 4x_3 = 0 \Rightarrow -4x_3 + 4x_3 = 0 \Rightarrow 0 = 0$$

$$(-2x_3, x_3, x_3) = x_3(-2, 1, 1)$$

$$\Rightarrow \text{Ker } T = \mathbb{L}\{(-2, 1, 1)\}$$

jezero je linearni operator jednog vektora

$$\text{def } T = \dim(\text{Ker } T) = 1$$

$$\text{Im } T = \{Ax \mid x \in \mathbb{R}^3\}$$

$$= \{x_1(0,1,0,2) + x_2(0,1,1,0) + x_3(0,1,-1,4)\}$$

$$\text{Im } T = x_1(0,1,0,2) + x_2(0,1,1,0) + x_3(0,1,-1,4) \\ = \mathcal{L}\{(0,1,0,2), (0,1,1,0), (0,1,-1,4)\} \equiv$$

treba provjeriti da li su lin. nezavisni

$$x_1(0,1,0,2) + x_2(0,1,1,0) + x_3(0,1,-1,4) = 0$$

$$A = \begin{pmatrix} 0 & 1 & 0 & 2 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & -1 & 4 \end{pmatrix} \xrightarrow{\substack{(-1) \\ (-1) \\ (-1)}} \sim \begin{pmatrix} 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & -1 & 2 \end{pmatrix} \xrightarrow{(-1)} \sim \begin{pmatrix} 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\text{rang } A = 2$$

$$\equiv \mathcal{L}\{(0,1,0,2), (0,0,1,-2)\}$$

$$\text{rang } T = \dim(\text{Im } T) = 2 \rightarrow \text{lin. operator s 2 lin. nezavisnih vektora}$$

$$\text{Provjera teoreme: } \dim \mathbb{R}^3 = \text{def } T + \text{rang } T$$

$$3 = 1 + 2 \quad \checkmark$$

63. Neka je $\{b_1, b_2, b_3\}$ baza trodimenzionalnog v.p. V i neka je $T: V \rightarrow V$ linearni operator definisan sa:

$$T(b_1) = b_1 + b_2 - b_3$$

$$T(b_2) = b_1 - b_2 + b_3$$

$$T(b_3) = b_1 - 3b_2 + 3b_3$$

Naci $\text{def } T$ i $\text{rang } T$.

$$\text{def } T = 1$$

$$\text{rang } T = 2$$

prva jezgra i sliku

67. $A \in \mathcal{L}(\mathbb{R}^4, \mathbb{R}^4)$ tj. A je lin. operator $A: \mathbb{R}^4 \rightarrow \mathbb{R}^4$
 definisan sa $A(x, y, z, t) = (x+2y+3z, 2x+3y+t, x-3z+2t, -y+t)$
 Obrediti jednu bazu prostora $\text{Ker } A$, i $\text{Im } A$.

$$\text{Ker } A = \{x \in \mathbb{R}^4 \mid Ax = 0\}$$

(0, 0, 0, 0) - iz prostora slike

$$= \{(x, y, z, t) \mid (x+2y+3z, 2x+3y+t, x-3z+2t, -y+t) = (0, 0, 0, 0)\}$$

$$\begin{array}{rcl} x+2y+3z & = & 0 \\ 2x+3y+t & = & 0 \\ x-3z+2t & = & 0 \\ -y+t & = & 0 \end{array}$$

$$\begin{array}{rcl} x+2y+3z & = & 0 \\ 2x+3y+t & = & 0 \quad |(-1) \\ 2x+2y+2t & = & 0 \\ -y+t & = & 0 \end{array}$$

$$\begin{array}{rcl} x+2y+3z & = & 0 \\ 2x+3y+t & = & 0 \\ -y+t & = & 0 \\ -y+t & = & 0 \end{array} \quad \left. \begin{array}{l} -2t+2t+3z=0 \\ 2x+t=0 \\ -y+t=0 \end{array} \right\} \begin{array}{l} z=0 \\ x=-2t \\ y=t \end{array}$$

$$\Rightarrow (-2t, t, 0, t) = t(-2, 1, 0, 1)$$

$$\Rightarrow \text{Ker } A = \mathbb{L}\{(-2, 1, 0, 1)\}$$

$\Rightarrow \dim A = 1$ jedan jedini vektor je baza $\text{Ker } A$

$$\begin{aligned} \text{Im } A &= \{Ax \mid x \in \mathbb{R}^4\} = \{ \\ &= \{(x+2y+3z, 2x+3y+t, x-3z+2t, -y+t) \mid (x, y, z, t) \in \mathbb{R}^4\} \\ &= \{x(1, 2, 1, 0) + y(2, 3, 0, -1) + z(3, 0, -3, 0) + t(0, 1, 2, 1) \mid (x, y, z, t) \in \mathbb{R}^4\} \\ &= \mathbb{L}\{(1, 2, 1, 0), (2, 3, 0, -1), (3, 0, -3, 0), (0, 1, 2, 1)\} \end{aligned}$$

$$\begin{pmatrix} 1 & 2 & 1 & 0 \\ 2 & 3 & 0 & -1 \\ 3 & 0 & -3 & 0 \\ 0 & 1 & 2 & 1 \end{pmatrix} \xrightarrow{\substack{R_2 \leftarrow R_2 - 2R_1 \\ R_3 \leftarrow R_3 - 3R_1}} \begin{pmatrix} 1 & 2 & 1 & 0 \\ 0 & -1 & -2 & -1 \\ 0 & -6 & -6 & 0 \\ 0 & 1 & 2 & 1 \end{pmatrix} \xrightarrow{\substack{R_3 \leftarrow R_3 + 6R_2 \\ R_4 \leftarrow R_4 + R_2}} \begin{pmatrix} 1 & 2 & 1 & 0 \\ 0 & -1 & -2 & -1 \\ 0 & 0 & -18 & -6 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$= \mathcal{L} \left\{ (1, 2, 1, 0), (0, -1, -2, -1), (0, 0, -18, -6) \right\}$$

$$= \mathcal{L} \left\{ (1, 2, 1, 0), (0, 1, 2, 1), (0, 0, 3, 1) \right\}$$

dimensi basis B proročara ImA

$$\Rightarrow \text{rang } A = 3$$

ZADACA:

63. $\{b_1, b_2, b_3\}$ A: $V \rightarrow V$ linearni operator definisan sa:

$$Ab_1 = b_1 + b_2 - b_3$$

$$Ab_2 = b_1 - b_2 + b_3$$

$$Ab_3 = b_1 - 3b_2 + 3b_3$$

$$\text{def } A = ? \quad \text{rang } A = ?$$

$$\text{def } A = \dim(\text{Ker } A); \quad \text{rang } A = \dim(\text{Im}(A))$$

$$\text{Ker } A = \{x \in V : Ax = 0\} = \{(b_1, b_2, b_3) \mid (Ab_1, Ab_2, Ab_3) = (0, 0, 0)\}$$

$$\left. \begin{array}{l} b_1 + b_2 - b_3 = 0 \\ b_1 - b_2 + b_3 = 0 \end{array} \right\} + 2b_1 = 0 \Rightarrow b_1 = 0$$

$$\underline{b_1 - 3b_2 + 3b_3 = 0} \quad -3b_2 = -3b_3 \Rightarrow b_2 = b_3$$

$$(0, b_2, b_2) = b_2(0, 1, 1)$$

$$\text{Ker } A = \mathcal{L} \{ (0, 1, 1) \} \Rightarrow \text{def } A = 1$$

$$\text{Im } A = \{y \in V : (\exists x \in V) y = Ax\} = (Ab_1, Ab_2, Ab_3)$$

$$= \{(b_1 + b_2 - b_3, b_1 - b_2 + b_3, b_1 - 3b_2 + 3b_3)\}$$

$$= \{b_1(1, 1, 1) + b_2(1, -1, -3) + b_3(-1, 1, 3)\}$$

$$= \mathcal{L} \{ (1, 1, 1), (1, -1, -3), (-1, 1, 3) \}^*$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & -3 \\ -1 & 1 & 3 \end{pmatrix} \sim \begin{pmatrix} 2 & 0 & -2 \\ 1 & -1 & -3 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \text{rang } A = 2$$

$$\cong \mathcal{L}\{(2, 0, -2), (1, -1, -3)\}$$

$$\text{rang } A + \dim A = 3$$

$$2 + 1 = 3 \quad \checkmark$$

$$61. \{ \overset{e_1}{(8, -6, 7)}, \overset{e_2}{(-16, 7, -13)}, \overset{e_3}{(9, -3, 7)} \} \text{ baza } \mathbb{R}^3$$

$$\begin{pmatrix} 1 & -18 & 15 \\ -1 & -22 & 20 \\ 1 & -25 & 22 \end{pmatrix}$$

Naći mat. istog operatora u bazi $\{ \overset{x_1}{(1, -2, 1)}, \overset{x_2}{(3, -1, 2)}, \overset{x_3}{(2, 1, 2)} \}$

$$f(\overset{x_1}{(1, -2, 1)}) = \alpha_1(\overset{x_1}{(1, -2, 1)}) + \alpha_2(\overset{x_2}{(3, -1, 2)}) + \alpha_3(\overset{x_3}{(2, 1, 2)})$$

$$\alpha_1 + 3\alpha_2 + 2\alpha_3 = 1 \quad | \cdot (-1) \quad 33$$

$$-2\alpha_1 - \alpha_2 + \alpha_3 = -2 \quad -16$$

$$\alpha_1 + 2\alpha_2 + 2\alpha_3 = 1 \quad 27$$

$$\alpha_1 + 3\alpha_2 + 2\alpha_3 = 1$$

$$\alpha_2 = -33 + 27 \Rightarrow \alpha_2 = 6$$

$$-2\alpha_1 - \alpha_2 + \alpha_3 = -2$$

$$\alpha_1 + 2\alpha_3 = 15 \quad | \cdot 2$$

$$-2\alpha_1 + \alpha_3 = 10$$

$$5\alpha_3 = 20$$

$$\alpha_3 = 4$$

$$\alpha_1 = 7$$

$$-\alpha_2 = 0 \Rightarrow \alpha_2 = 0$$

$$\alpha_1 + 2\alpha_3 = 1 \quad | \cdot 2$$

$$-2\alpha_1 + \alpha_3 = -2$$

$$5\alpha_3 = 0 \Rightarrow \alpha_3 = 0 \Rightarrow \alpha_1 = 1$$

$$f(\overset{x_2}{(3, -1, 2)}) = \alpha_1(\overset{x_1}{(1, -2, 1)}) + \alpha_2(\overset{x_2}{(3, -1, 2)}) + \alpha_3(\overset{x_3}{(2, 1, 2)})$$

$$\alpha_1 + 3\alpha_2 + 2\alpha_3 = 3 \quad | \cdot (-1) \quad -17$$

$$-\alpha_2 = 2 \Rightarrow \alpha_2 = -2$$

$$-2\alpha_1 - \alpha_2 + \alpha_3 = -1 \quad 28$$

$$\alpha_1 + 2\alpha_3 = -11 \quad | \cdot 2$$

$$-2\alpha_1 + \alpha_3 = 27$$

$$\alpha_1 + 2\alpha_2 + 2\alpha_3 = 2 \quad -15$$

$$5\alpha_3 = 5$$

$$\alpha_3 = 1$$

$$\alpha_1 = -13$$

$$\alpha_1 + 3\alpha_2 + 2\alpha_3 = 3$$

$$-2\alpha_1 - \alpha_2 + \alpha_3 = -1$$

$$-\alpha_2 = -1 \Rightarrow \alpha_2 = 1$$

$$d_1 + 2d_3 = 2 \quad | \cdot 2 \quad - \quad -$$

$$-2d_1 - 2d_3 = -4$$

$$5d_3 = 0 \Rightarrow d_1 = d_3 = 0$$

$$f(2, 1, 2) = d_1(1, -2, 1) + d_2(3, -1, 2) + d_3(2, 1, 2)$$

$$-d_1 + 3d_2 + 2d_3 = 2 \quad | \cdot (-1) \quad -2$$

$$-2d_1 - d_2 + d_3 = 1 \quad -16$$

$$d_1 + 2d_2 + 2d_3 = 2 \quad -1$$

$$\Rightarrow d_2 = 0$$

$$d_1 + 2d_3 = 2 \quad | \cdot 2$$

$$-2d_1 + d_3 = 1 \quad \leftarrow$$

$$5d_3 = 5 \Rightarrow d_3 = 1 \quad d_1 = 0$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 7 & -13 & 7 \\ 6 & -2 & -1 \\ 4 & 1 & -3 \end{pmatrix}$$

$$f(8, -6, 7) = 1 \cdot e_1 - 1 \cdot e_2 + 1 \cdot e_3 = (33, -16, 27) = f(e_1) \quad ? = (1, -1, 1)$$

$$f(-16, 7, -13) = -18 \cdot e_1 - 22 \cdot e_2 - 25 \cdot e_3 = (-17, 29, -15) = f(e_2) \quad ? = (-18, -22, -25)$$

$$f(9, -3, 7) = 15e_1 + 20e_2 + 22e_3 = (-2, -16, -1) = f(e_3) \quad ? = (15, 20, 22)$$

$$f(1, -2, 1) = f(1 \cdot e_1 + 1 \cdot e_2 + 1 \cdot e_3) = f(e_1) + f(e_2) + f(e_3) = (14, -3, 11) \quad /$$

$$f(3, -1, 2) = f(1 \cdot e_1 + 2 \cdot e_2 + 3 \cdot e_3) = f(e_1) + 2f(e_2) + 3f(e_3) = (-7, -6, -6) \quad /$$

$$f(2, 1, 2) = f(-3e_1 - 5e_2 - 6e_3) = -3f(e_1) - 5f(e_2) - 6f(e_3) = (-2, -1, 0) \quad /$$

$$A = \begin{pmatrix} 14 & -7 & -2 \\ -3 & -6 & -1 \\ 11 & -6 & 0 \end{pmatrix} = \sum \alpha_i b_i$$

$$d_1 + 3d_2 + 2d_3 = 14 \quad \left\{ \begin{array}{l} d_1 = 1 \quad 14 = 14 \\ d_2 = 3 - 2 - 5 + 2 = 3 \\ d_3 = 2 \end{array} \right.$$

$$-2d_1 - d_2 + d_3 = -3$$

$$d_1 + 2d_2 + 2d_3 = 11$$

$$\text{mat}_B f = \begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix}$$

57. $f(x) = e^{ax} \cdot P(x)$, $a \in \mathbb{R}$, $a \neq 0$ $\deg P(x) \leq 3$

Dokazati da je operator definisan sa $D(f) = f'$ lin. i maći mat. tog. op. u odnosu na bazu:

$$B = \{e^{ax}, xe^{ax}, x^2e^{ax}, x^3e^{ax}\}$$

$$D(\alpha f + \beta g) = (\alpha f + \beta g)' = \alpha f' + \beta g' = \alpha \cdot D(f) + \beta D(g)$$

$$D(e^{ax}) = a \cdot e^{ax} = (a, 0, 0, 0)$$

$$D(xe^{ax}) = e^{ax} + x \cdot ae^{ax} = (1, a, 0, 0)$$

$$D(x^2e^{ax}) = 2xe^{ax} + x^2 \cdot ae^{ax} = (0, 2, a, 0)$$

$$D(x^3e^{ax}) = 3x^2e^{ax} + x^3ae^{ax} = (0, 0, 3, a)$$

$$A_D = \begin{pmatrix} a & 1 & 0 & 0 \\ 0 & a & 2 & 0 \\ 0 & 0 & a & 3 \\ 0 & 0 & 0 & a \end{pmatrix}$$

55. $f: V \rightarrow V$ V je 3-dim. v.p.

Da li su:

c) $f(x) = (2x_1 + x_2, x_1 + x_3, x_3^2)$

d) $f(x) = (x_1 - x_2 + x_3, x_3, x_2)$

lin. operatori, ako jesu maći njihove mat. u bazi u kojoj su zadane koordinate vektora x : $f(x)$

c) $f(x) = (2x_1 + x_2, x_1 + x_3, x_3^2)$

$$\begin{aligned} f(\alpha x + \beta y) &= f(\underbrace{\alpha x_1 + \beta y_1}_{x_1}, \underbrace{\alpha x_2 + \beta y_2}_{x_2}, \underbrace{\alpha x_3 + \beta y_3}_{x_3}) = \\ &= (2\alpha x_1 + 2\beta y_1 + \alpha x_2 + \beta y_2, \alpha x_1 + \beta y_1 + \alpha x_3 + \beta y_3, \alpha^2 x_3^2 + 2\alpha\beta x_3 y_3 + \beta^2 y_3^2) \\ &= (\alpha(2x_1 + x_2) + \beta(2y_1 + y_2), \alpha(x_1 + x_3) + \beta(y_1 + y_3), (\alpha x_3 + \beta y_3)^2) \\ &= \alpha(2x_1 + x_2, x_1 + x_3, \end{aligned}$$

nije lin. operator

$$d) f(x) = (x_1 - x_2 + x_3, x_3, x_2) \quad x, y \in W, \lambda, \mu \in F$$

$$\begin{aligned} f(\lambda x + \mu y) &= f(\lambda x_1 + \mu y_1, \lambda x_2 + \mu y_2, \lambda x_3 + \mu y_3) = \\ &= (\lambda x_1 + \mu y_1 - \lambda x_2 - \mu y_2 + \lambda x_3 + \mu y_3, \lambda x_3 + \mu y_3, \lambda x_2 + \mu y_2) \\ &= (\lambda(x_1 - x_2 + x_3) + \mu(y_1 - y_2 + y_3), \lambda x_3 + \mu y_3, \lambda x_2 + \mu y_2) \\ &= \lambda(x_1 - x_2 + x_3, x_3, x_2) + \mu(y_1 - y_2 + y_3, y_3, y_2) \\ &= \lambda f(x) + \mu f(y) \end{aligned}$$

ješte lin. operator

$$B = \{e_1, e_2, e_3\}$$

$$f(e_1) = (1, 0, 0) = (1, 0, 0)$$

$$f(e_2) = (0, 1, 0) = (-1, 0, 1)$$

$$f(e_3) = (0, 0, 1) = (1, 1, 0)$$

$$A_f = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

54. Dokazati da postoji jedinstven lin. o. trodim. v.p. koji prevodi vektore a_1, a_2, a_3 u b_1, b_2, b_3 , redom. I moći mat. tog operatora u istoj bazi u kojoj su date i koordinate tih vektora.

$$b) a_1 = (2, 0, 3), a_2 = (4, 1, 5), a_3 = (3, 1, 2)$$

$$b_1 = (1, 2, -1), b_2 = (4, 5, -2), b_3 = (1, -1, 1)$$

$$f: A \rightarrow B$$

$$\lambda_1 a_1 + \lambda_2 a_2 + \lambda_3 a_3 = 0 \quad \text{lin. mez. ?}$$

$$2\lambda_1 + 4\lambda_2 + 3\lambda_3 = 0$$

$$\lambda_2 + \lambda_3 = 0$$

$$3\lambda_1 + 5\lambda_2 + 2\lambda_3 = 0$$

$$B = \begin{vmatrix} 2 & 4 & 3 \\ 0 & 1 & 1 \\ 3 & 5 & 2 \end{vmatrix} \xrightarrow{(-1)} \begin{vmatrix} 2 & 1 & 3 \\ 0 & 0 & 1 \\ 3 & 3 & 2 \end{vmatrix} = -1 \cdot (6 - 3) = -3 \neq 0 \Rightarrow \lambda_1 = \lambda_2 = \lambda_3 = 0$$

lin. mez. w

$\Rightarrow B(a_1, a_2, a_3)$ su lin. nez. i kako je trodim. v.p. $\Rightarrow B$ je baza

$\Rightarrow B$ lin. o.

Pa prema τ : Prostor V je potpuno određen ako su poznate slike elemenata baze; potrebno je odrediti i slike:

$$f(a_1) = f(2, 0, 3) = f(2 \cdot e_1 + 0 \cdot e_2 + 3 \cdot e_3) = 2f(e_1) + 3f(e_3) = (1, 2, -1) = e_1 + 2e_2 - e_3$$

$$f(a_2) = f(4, 1, 5) = 4f(e_1) + f(e_2) + 5f(e_3) = 4e_1 + 5e_2 - 2e_3$$

$$f(a_3) = f(3, 1, 2) = 3f(e_1) + f(e_2) + 2f(e_3) = e_1 - e_2 + e_3$$

$$2f(e_1) + 3f(e_3) = e_1 + 2e_2 - e_3$$

$$4f(e_1) + f(e_2) + 5f(e_3) = 4e_1 + 5e_2 - 2e_3 \quad \leftarrow$$

$$3f(e_1) + f(e_2) + 2f(e_3) = e_1 - e_2 + e_3 \quad / \cdot (-1)$$

$$2f(e_1) + 3f(e_3) = e_1 + 2e_2 - e_3 \quad \leftarrow$$

$$f(e_1) + 3f(e_3) = 3e_1 + 6e_2 - 3e_3 \quad / \cdot (-1)$$

$$f(e_1) = -2e_1 + 4e_2 + 2e_3 = \underline{\underline{(-2, 4, 2)}} // = \frac{1}{3}(-6, 12, 6)$$

$$f(e_2) = \frac{e_1 + 2e_2 - e_3 + 4e_1 + 8e_2 + 4e_3}{3} - \frac{5e_1 + 10e_2 - 5e_3}{3} = \underline{\underline{\frac{1}{3}(5, 10, -5)}}$$

$$f(e_2) = \frac{e_1 - e_2 + e_3 + 6e_1 + 12e_2 - 6e_3}{3} + \frac{2}{3}(5e_1 + 10e_2 - 5e_3) = \underline{\underline{\frac{1}{3}(11, 13, -5)}}$$

$$A_f = \frac{1}{3} \begin{pmatrix} -6 & 11 & 5 \\ -12 & 13 & 10 \\ 6 & -5 & -5 \end{pmatrix}$$

53. $f: M_2 \rightarrow M_2 \quad f(X) = AX + XB$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}$$

a) Da li je lin. operator?

$$\begin{aligned} f(\alpha X + \beta Y) &= A(\alpha X + \beta Y) + (\alpha X + \beta Y)B \\ &= A \cdot \alpha X + A \cdot \beta Y + \alpha X \cdot B + \beta Y \cdot B \\ &= \alpha(AX) + \beta(AY) + \alpha(X \cdot B) + \beta(Y \cdot B) \\ &= \alpha(AX + XB) + \beta(AY + YB) \\ &= \alpha f(X) + \beta f(Y) \Rightarrow \text{jest lin. operator} \end{aligned}$$

b) Naci mat. operatora f u odnosu na bazu

$$B = \left\{ \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right\}$$

$\begin{matrix} E_1 & E_2 & E_3 & E_4 \end{matrix}$

$$f(E_1) = A \cdot E_1 + E_1 \cdot B = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} =$$

$$= \begin{bmatrix} 0 \cdot a + 0 \cdot b & a \cdot 0 + b \cdot 1 \\ c \cdot 0 + d \cdot 0 & c \cdot 0 + d \cdot 1 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ g & h \end{bmatrix} = \begin{bmatrix} 0 & b \\ g & d+h \end{bmatrix}$$

$$= 0 \cdot E_1 + b \cdot E_3 + g \cdot E_2 + (d+h) E_1 = (d+h, g, b, 0)$$

$$f(E_2) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} b & 0 \\ d & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ e & f \end{bmatrix} = \begin{bmatrix} b & 0 \\ d+e & f \end{bmatrix}$$

$$= b \cdot E_1 + 0 \cdot E_3 + (d+e) E_2 + f \cdot E_1 = (f, d+e, 0, b)$$

$$f(E_3) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} 0 & a \\ 0 & c \end{bmatrix} + \begin{bmatrix} g & h \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} g & a+h \\ 0 & c \end{bmatrix}$$

$$= g \cdot E_1 + (a+h) E_3 + 0 \cdot E_2 + c \cdot E_1 = (c, 0, a+h, g)$$

$$f(E_4) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} a & 0 \\ c & 0 \end{bmatrix} + \begin{bmatrix} e & f \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a+e & f \\ c & 0 \end{bmatrix}$$

$$= (a+e) E_1 + f \cdot E_3 + c \cdot E_2 + 0 \cdot E_1 = (0, c, f, a+e)$$

$$A_f = \begin{pmatrix} d+h & f & c & 0 \\ g & d+e & 0 & c \\ b & 0 & a+h & f \\ 0 & b & g & a+e \end{pmatrix}$$

52. $f: M_2 \rightarrow M_2$ nad \mathbb{R}

$$f(X) = A \cdot X \cdot B \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}$$

a) Da li je lin. operator?

$$\begin{aligned} f(\alpha X + \beta Y) &= A \cdot (\alpha X + \beta Y) \cdot B = (A \cdot \alpha X + A \cdot \beta Y) \cdot B = A \cdot \alpha X \cdot B + A \cdot \beta Y \cdot B \\ &= \alpha \cdot A \cdot X \cdot B + \beta \cdot A \cdot Y \cdot B = \alpha \cdot f(X) + \beta \cdot f(Y) \end{aligned}$$

jest lin. operator.

b) Naci mat. operatora u odnosu na bazu:

$$B = \left\{ \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}_{E_1}, \underbrace{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_{E_2}, \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}_{E_3}, \underbrace{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}}_{E_4} \right\}$$

$$\begin{aligned} f(E_1) &= A \cdot E_1 \cdot B = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} a & 0 \\ c & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} ae & af \\ ce & cf \end{bmatrix} \\ &= cf \cdot E_4 + ce \cdot E_3 + af \cdot E_2 + ae \cdot E_1 = (ae, af, ce, cf) \end{aligned}$$

$$\begin{aligned} f(E_2) &= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} 0 & a \\ 0 & c \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} ag & ah \\ cg & ch \end{bmatrix} \\ &= (ag, ah, cg, ch) \end{aligned}$$

$$\begin{aligned} f(E_3) &= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ d & 0 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} be & bf \\ de & df \end{bmatrix} \\ &= (be, bf, de, df) \end{aligned}$$

$$\begin{aligned} f(E_4) &= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} 0 & b \\ 0 & d \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} bg & bh \\ dg & dh \end{bmatrix} \\ &= (bg, bh, dg, dh) \end{aligned}$$

$$A_f = \begin{bmatrix} ae & ag & be & bg \\ af & ah & bf & bh \\ ce & cg & de & dg \\ cf & ch & df & dh \end{bmatrix}$$

65. Neka je $A: M_2(\mathbb{R}) \rightarrow M_2(\mathbb{R}); A(X) = \frac{1}{2}(X - X^T)$

a) Dokazati da je A lin. op.

b) Odrediti matricu operatora A u standardnoj bazi

c) Naći $\text{Ker } A$, $\text{Im } A$, njihove dimenzije i po jednu njihovu bazu

d) Odrediti karakteristični i minimalni polinom matrice operatora.

e) Naći $A^n, n \in \mathbb{N}$

$$b) B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

$$A = \text{mat}_B A = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \text{matrica operatora}$$

$$c) \text{Ker } A = \left\{ X \mid A(X) = 0 \right\}$$

$$= \left\{ X \mid \frac{1}{2}(X - X^T) = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \right\} \quad \text{ovo će biti } = 0 \text{ ako su } X \text{ i } X^T \text{ simetrične}$$

$$= \left\{ X \mid X = X^T \right\} = \left\{ \begin{pmatrix} a & b \\ b & c \end{pmatrix} \mid a, b, c \in \mathbb{R} \right\} =$$

$$= \left\{ a \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + b \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + c \cdot \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \mid a, b, c \in \mathbb{R} \right\}$$

$$= \text{span} \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

3 lin. nezavisna vektora (provjeriti lin. nezab.)

$$\dim R = 3$$

$$\sum \lambda_i R_i = 0$$

$$\lambda_1 = 0$$

$$\lambda_2 = 0$$

$$\lambda_3 = 0$$

$$\lambda_4 = 0$$

$$\text{Im } A = \{A(X) \mid X \in M_2(\mathbb{R})\}$$

$$= \left\{ \frac{1}{2}(X - X^T) \mid X \in M_2(\mathbb{R}) \right\}$$

$$= \left\{ \frac{1}{2} \begin{pmatrix} 0 & b-c \\ c-b & 0 \end{pmatrix} \mid b, c \in \mathbb{R} \right\} = \left\{ (b-c) \begin{pmatrix} 0 & \frac{1}{2} \\ -\frac{1}{2} & 0 \end{pmatrix} \mid (b-c) \in \mathbb{R} \right\}$$

$$= \mathbb{R} \left(\begin{pmatrix} 0 & \frac{1}{2} \\ -\frac{1}{2} & 0 \end{pmatrix} \right)$$

$$\text{rang } A = 1 = \dim \text{Im } A \quad 2+1=3$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} - \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} 0 & b-c \\ c-b & 0 \end{pmatrix}$$

d) Karakteristični polinom matrice (mat. mora biti kvadratna)

$$(A - \lambda I) = \begin{vmatrix} a_{11} - \lambda & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} - \lambda & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} - \lambda \end{vmatrix}$$

I. Svaka kvadratna matrica anulira svoj karakteristični polinom (Keli-Hamiltonov teorem)

Minimalni polinom mat. je minimalni faktor karakterističnog polinoma kojeg anulira ta matrica.

$$P_*(\lambda) = \begin{vmatrix} -\lambda & 0 & 0 & 0 \\ 0 & \frac{1}{2} - \lambda & -\frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} - \lambda & 0 \\ 0 & 0 & 0 & -\lambda \end{vmatrix} = (-\lambda) \cdot \begin{vmatrix} \frac{1}{2} & -\frac{1}{2} & 0 \\ -\frac{1}{2} & \frac{1}{2} - \lambda & 0 \\ 0 & 0 & -\lambda \end{vmatrix} =$$

$$= (-\lambda)(-\lambda) \left(\left(\frac{1}{2} - \lambda \right)^2 - \frac{1}{4} \right) = \lambda^2 \cdot \left(\frac{1}{2} - \lambda - \frac{1}{2} \right) \left(\frac{1}{2} - \lambda + \frac{1}{2} \right) =$$

$$= \lambda^3 (\lambda - 1) \rightarrow \text{karakteristični pol. operatora tj. njegova matrice}$$

Prema K.H. teoremu:

$$A^3 \cdot (A - I) = 0 \Rightarrow A^4 = A^3$$

Minimalni pol. ima iste nule kao i karakteristični pol.; pa su kandidati za nule:

$$\lambda(\lambda-1), \lambda^2(\lambda-1), \lambda^3(\lambda-1)$$

treba proveriti da li je:

$$A \cdot (A - I) \stackrel{?}{=} 0$$

$$\begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

\Rightarrow minimalni pol. je $\lambda(\lambda-1)$

$$e) A \cdot (A - I) = 0$$

$$A^2 = A \quad \vee$$

$$A^3 = A^2 \cdot A = A \cdot A = A^2 = A$$

$$A^4 = \dots = A$$

$$A^m = A$$

~~Mat. indukcijom: $P: A^m = A$~~

$$F: A^{m+1} = A$$

$$A^{m+1} = A^m \cdot A = A \cdot A = A^2 = A$$